



Comparative Analysis of Spacecraft Schedule by Classical and Quantum Monte Carlo Simulations

by

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Acknowledgements

- Tom Coonce (NASA) and Charles D. Hunt (NASA)
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Outline

- Study Approach
- Interviewees
- Common Schedule
- “Risk Driver” Classical Approach
- Quantum Approach
- Overall Results
- Conclusions & Recommendations



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Study Approach

- In mid-2008, I was made aware of an approach to schedule risk that involved using quantum mechanics
- While somewhat skeptical, I convinced NASA cost management to modestly fund a study
- The study was designed not to understand how quantum mechanics produces the confidence level of reaching a planned milestone
- The study was designed to compare the results of the quantum mechanics approach to the more trusted traditional “classical” approach to schedule risk analysis
- The idea was to see if using the same schedule for analysis the results from both approaches were anywhere near the same
- We did this knowing full well that results that were close or far apart from only one common schedule example would not “prove” anything
- It could, however, give an indication that further experimental use of the quantum approach was warranted



Interviewees

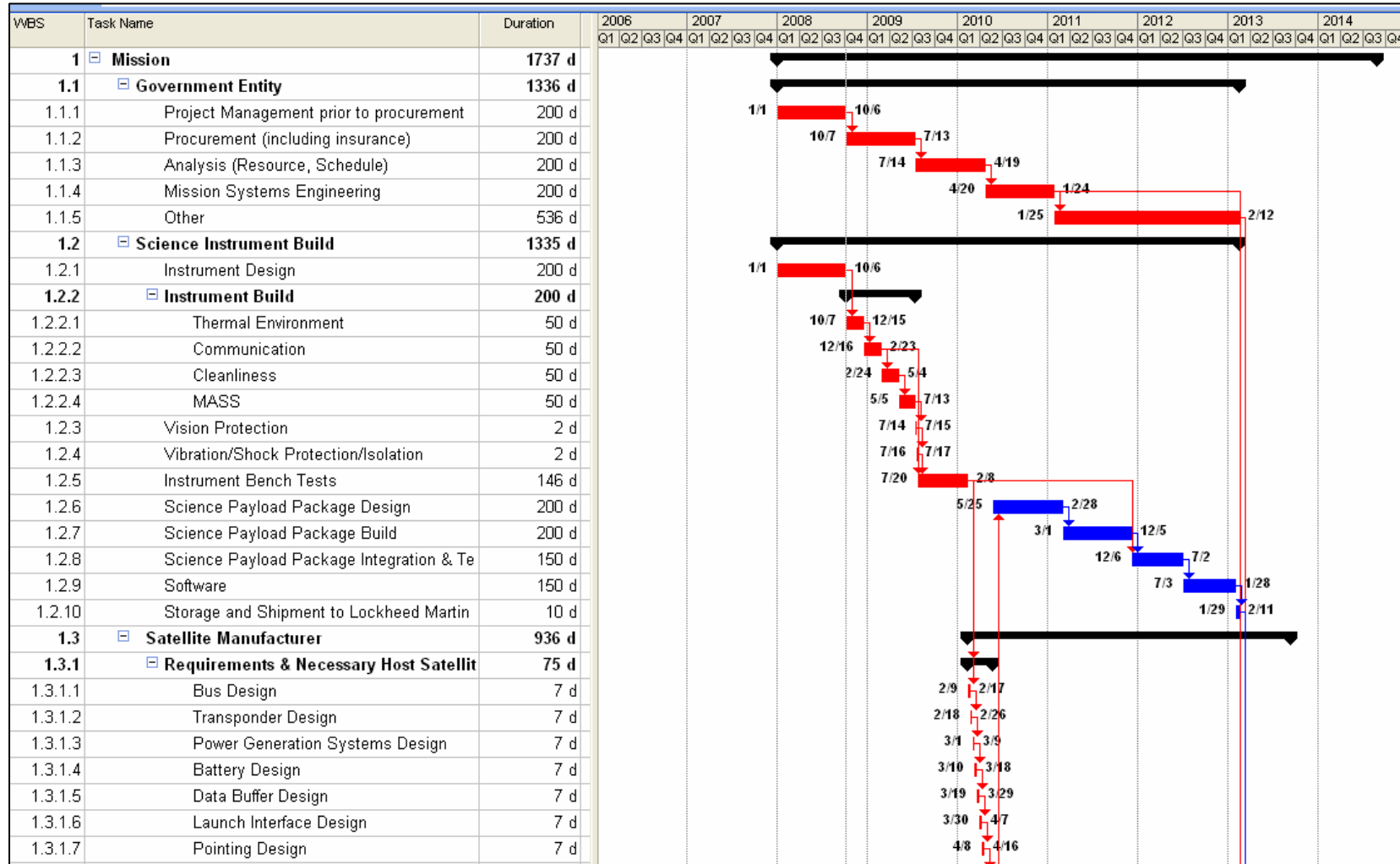
- Tom Coonce, NASA
- Charles D. Hunt NASA
- David R. Graham, USAF

(Usually there are 30 or so interviewees from high-level to discipline leads and even contractors. This provides the context and credibility for the results.)



Schedule Used for Both Approaches

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Project Summary Integrated Schedule



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“Risk Driver” Classical Approach



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“Risk Driver” Classical Approach

- The traditional “classical” approach applies uncertainty on Low-ML-High estimates of duration as characterizations of activity-level triangular distributions
- The Risk Driver classical approach applied in this study focused uncertainty on the risks themselves
- Risks were then associated with activities and their task durations to characterize their distributions
- Risks took the form of estimates on risk likelihoods of occurrence and factors representing the effects risks could have on the planned activity duration estimates to represent the Low-ML-High durations on activity triangular distributions



Risk Factors' Likelihoods & Range Estimate Factors



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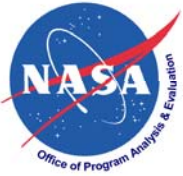
	Risk Factor	Probability	Minimum	Most Likely	Maximum
1	Because multi-year funding, funding may not be stable	55%	100%	106%	116%
2	Some small suppliers may not be stable	20%	100%	106%	112%
3	Since technology is immature, the TRL may be lower than assessed	50%	100%	110%	120%
4	Requirements may not be stable, may be volatile	55%	100%	108%	114%
5	May not have accurate est. of reuse of software / hardware	90%	98%	106%	114%
6	Immature design, may not know the weights or mass of components	70%	98%	102%	108%
7	May not have estimated accurately the S/W Lines of Code	65%	98%	104%	116%
8	There may be uncertainty in the Launch Vehicle	45%	100%	104%	108%
9	Project complexity may lead to poor staffing of multi-contractor teams	50%	100%	104%	110%
10	There may be conflicting schedules and workload	15%	94%	102%	104%
11	Article may fail systems testing and require re-testing	60%	102%	114%	126%
12	Coordination between project sites may be difficult	40%	100%	104%	108%
13	Sufficient trained/experienced technical personnel may not be available	60%	100%	106%	112%



Risk Factor Assignments to Activities



RF #	Assignment of the Risk Factors	Government Entity	Science Instrument Build	Satellite Manufacturing	Launch & Vehicle Services	Launch Facility
1	Because multi-year funding, funding may not be stable	X	X	X	X	X
2	Some small suppliers may not be stable		X		X	
3	Since technology is immature, the TRL may be lower than assessed		X	X		
4	Requirements may not be stable, may be volatile		X	X		
5	May not have accurate est. of reuse of software / hardware		X			
6	Immature design, may not know the weights or mass of components	X		X		
7	May not have estimated accurately the S/W Lines of Code		X			
8	There may be uncertainty in the Launch Vehicle				X	
9	Project complexity may lead to poor staffing of multi-contractor teams		X	X	X	
10	There may be conflicting schedules and workload	X	X	X	X	X
11	Article may fail systems testing and require re-testing			X	X	
12	Coordination between project sites may be difficult		X	X	X	
13	Sufficient trained/experienced technical personnel may not be available	X				



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Some Comments on Data

Interviewee	Prob.	Min	ML	Max
# 1	25%	100%	115%	140%
# 2	75%	100%	105%	110%
Average	50%	100%	110%	125%

Gather data from several people so we can get different inputs
Start with Averages, but sometimes round the values to avoid suggesting more accuracy than is available
On occasion some interviewees will be deemed to be more expert in the area and get greater weight



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Need to Adjust the Ranges to Account for Many Risks Assigned to Activity

Adjust the Ranges Because of Many Risks on Same Activity				
	Prob.	Min	ML	Max
Average	50%	95%	110%	125%
Adjust 60%	50%	98%	104%	110%

In schedule risk the impact of two risks can occur simultaneously rather than in series

The multiplicative nature of the Risk Factors approach tends to overstate the cumulative impact of several risks assigned to the same activity. We have many activities with multiple risks assigned

The Classical approach has used a factor of .4 (adjusting by .6) which seems to give reasonable results when there are 5-10 risks applied to the same activity. In Science Instrument Build, Satellite Manufacturing and Launch & Vehicle Services we have multiple risks assigned.



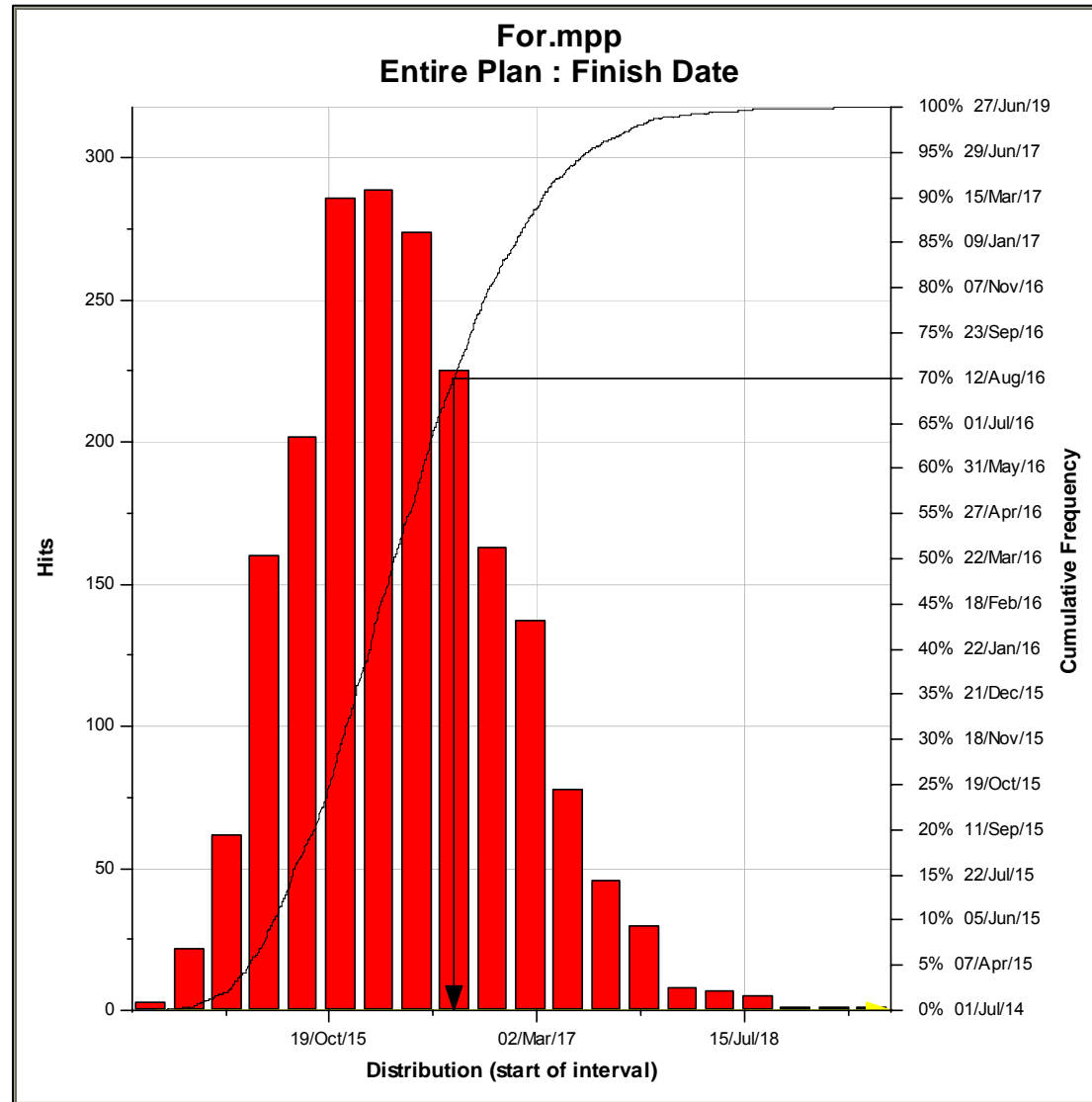
Risk Driver Classical Approach

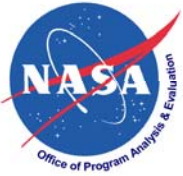


Schedule Risk Results

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Preliminary indications are that the P-70 target is 2 years delayed to 12 August 2016 from 27 August 2014





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Risk Factors Tornado Chart

Top 3 risks:
TRL may be low
Multi-year funding
Requirements not
Stable





Quantum Approach



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Bridge Between Quantum Mechanics & Schedule Risk

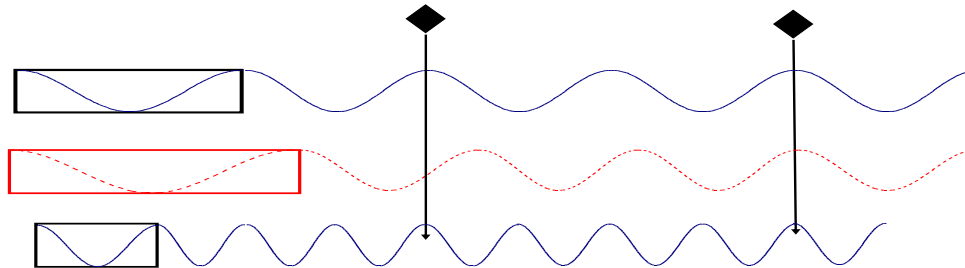
- Quantum mechanics is the study and prediction of elementary particle behavior
 - e.g., photons, electrons, neutrons, neutrinos, quarks, etc.
 - Elementary particles have both particle and “wave” characteristics
- The *activity* is the analog to the elementary particle in schedule risk
 - Activities have both particle and “wave” characteristics
 - Activities are driven by human behavior so quantum mechanics can be seen as modeling human behavior
- However, can't predict individual elementary particle behavior like normal size objects
- Can only predict elementary particle behavior probabilistically
 - Can say only that there is a probability that a photon will be in a specific location with a certain probabilistic confidence
- Quantum mechanics then works in the probabilistic realm which is the same way we traditionally treat schedule duration



Task “Wave” Interference Patterns



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$$\Delta Q = \left(\frac{\partial Q}{\partial \varphi_1} \frac{d\varphi_1}{dt} + \frac{\partial Q}{\partial \varphi_2} \frac{d\varphi_2}{dt} + \frac{\partial Q}{\partial \varphi_3} \frac{d\varphi_3}{dt} + \dots \right) \Delta t_{risk}$$

- It is the conjectural analogous wave-like properties of people’s managerial behavior performing tasks that the quantum approach assumes and takes advantage
- When the wave functions of particles (i.e., tasks) are coherent (i.e., peaks line up) and the tasks represented by the sinusoidal wave functions peak at the same time, the milestone is met. The top and bottom black boxes represent the planned tasks
- One wave period represents the task duration. The periods of the waves can be different as depicted. They line up at the milestones represented by the diamonds and the lines



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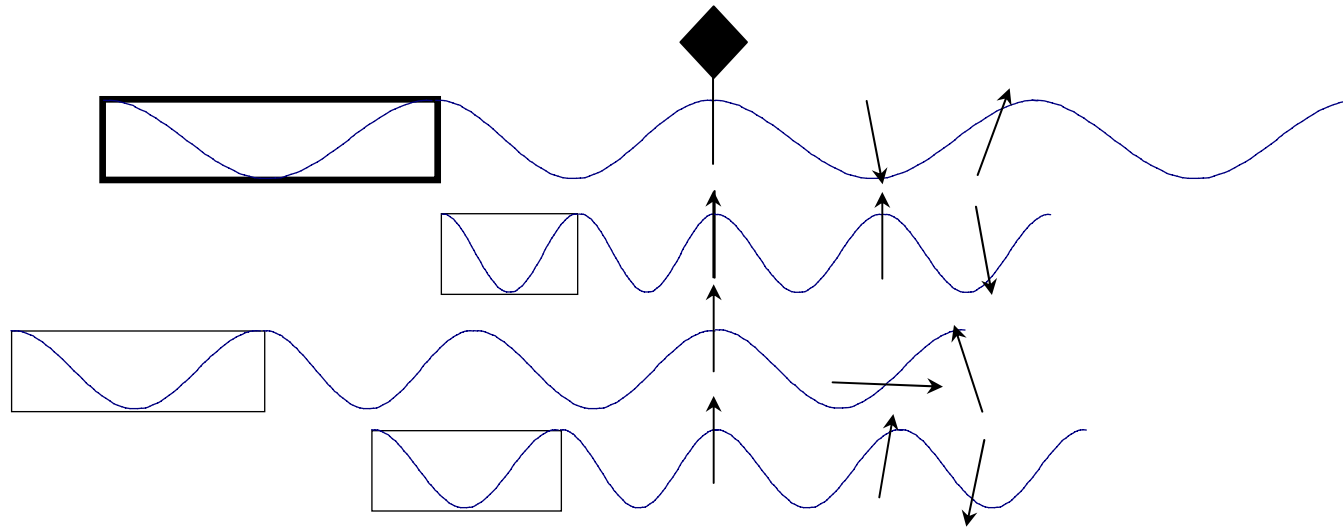
Three Dimensions of the Quantum Schedule Risk Approach

- There are three dimensions of risk at work in the quantum approach
 - **Project structure risks**
 - **Task duration risks**
 - **Risk register risks**
- **Project structure risks** are a function of the internal project schedule itself
 - Number of tasks; task durations; links; and, distance to milestone
- **Task duration risks** result from the natural coefficient of variation (CoV) of task durations within the project schedule as a function of monte carlo simulations that use the **Numerical Inverse Fourier Transform (NIFT)** method of summarizing random harmonics along the full time axis vice one point at a time as with individual task duration distributions in the classical application of monte carlo statistical summing (*in later chart*)
 - The natural CoV can be manually overridden by the user
- **Risk register risks** are implemented by identifying the likelihood and consequence qualitatively using the 5X5 risk matrix

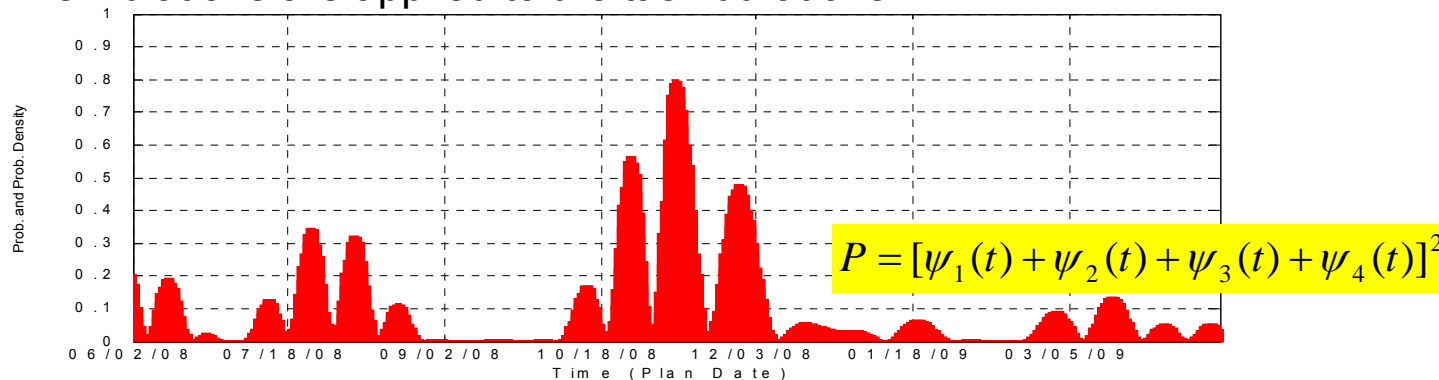


Project Structure Risk

Task “Wave” Interference Patterns



- This picture corresponds to the quantum condition where no monte carlo simulations are applied to the task durations

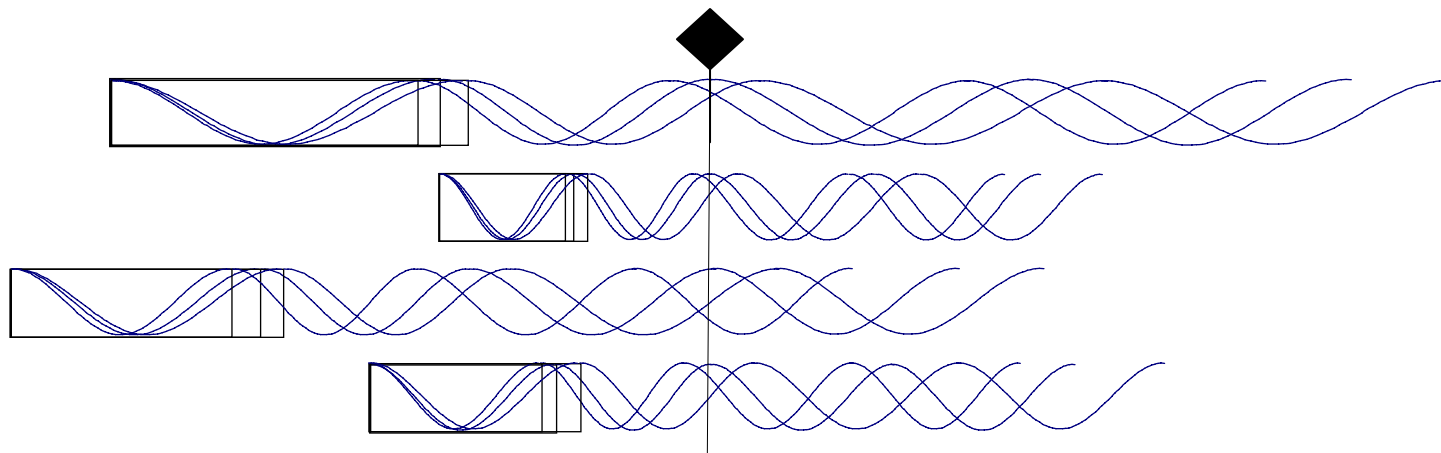


- The result is that the CoV is large
- Meeting the milestone is highest at the peaks but spread out



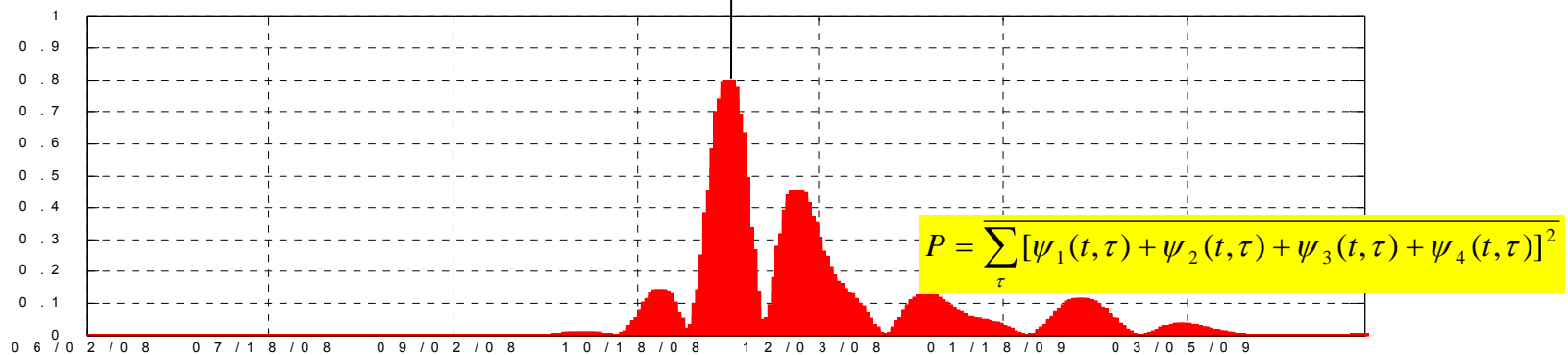
Task Duration Risk

300 Monte Carlo Simulated Project Samples



- This picture corresponds to the quantum condition where monte carlo simulations are applied to the task durations

Mean of milestone image is shifted **to later date**



- The result is that the CoV has been reduced
- Meeting the milestone is highest at the peaks and less spread out



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Risk Register Risks

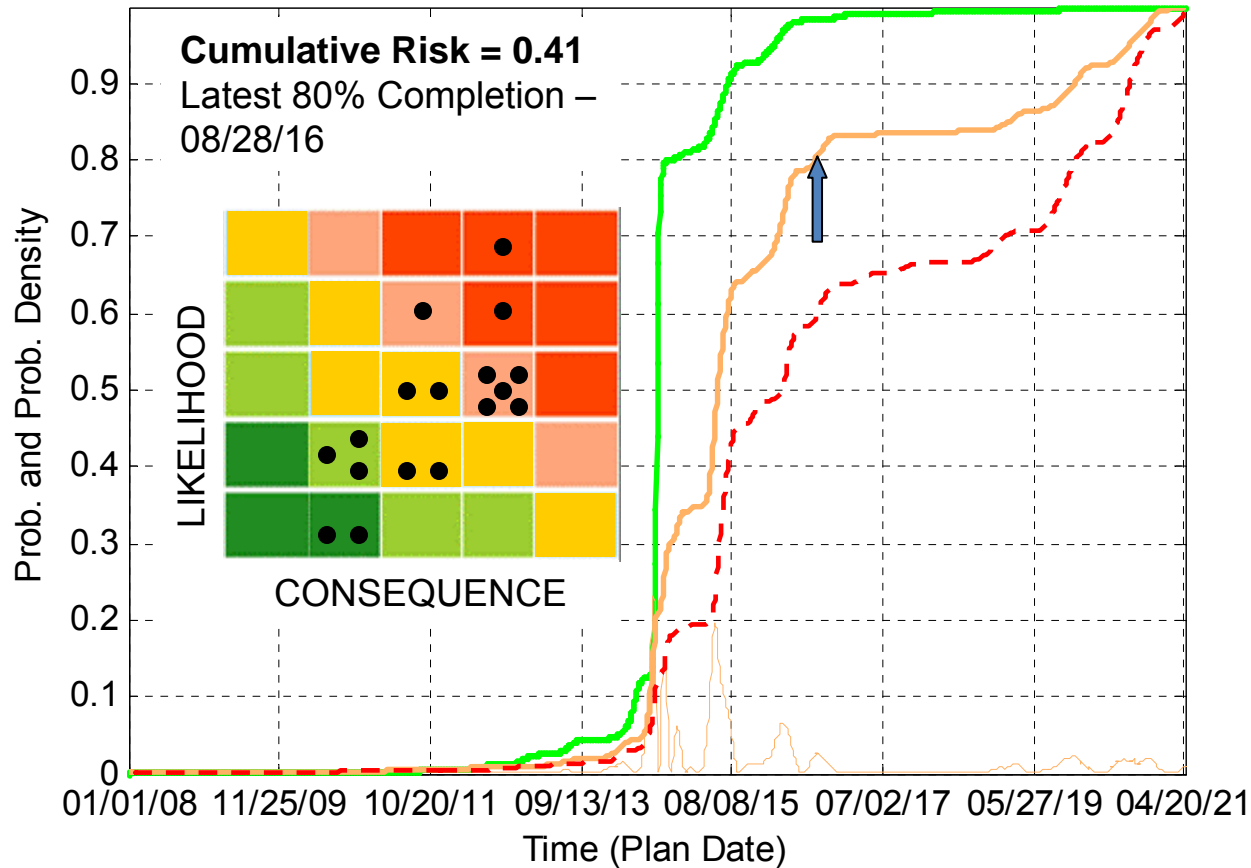
Quantum Risk Register

Risk Category	Risk Likelihood and Consequence				
Cost risks					
<input checked="" type="checkbox"/> Funding stability	Green	Orange	Red-Orange	Red	Dark Red
<input type="checkbox"/> Supplier financial viability	Green	Yellow	Orange	Red-Orange	Red
<input type="checkbox"/> Other	Green	Yellow	Orange	Red-Orange	Red
Performance Risks					
<input type="checkbox"/> Immature Technology - TRL was too low or assessed too high	Green	Yellow	Orange	Red-Orange	Red
<input type="checkbox"/> Requirements volatility	Green	Green	Yellow	Orange	Red-Orange
<input type="checkbox"/> High percent new design required	Green	Green	Yellow	Orange	Red-Orange
<input type="checkbox"/> Extent to which existing hardware or software can be reused	Green	Green	Green	Yellow	Orange
<input type="checkbox"/> Activities take longer because they are more complicated than estimated	Green	Green	Green	Green	Yellow

- There are 19 risk categories in the quantum risk register separated into 3 groups: Cost Risk, Performance Risk and Management Risk
- Entries are made by selecting a single square in the 5x5 risk matrix
- Each square has a pair of assignments associated with it: likelihood and consequence
- L=C=1 (upper right red square); L=C=0 (lower left green square)
- Formula for total risk: $CR = \sqrt{[(L_1C_1)^2 + (L_2C_2)^2 + \dots + (L_kC_k)^2 + 0.25(19 - k)]/19}$



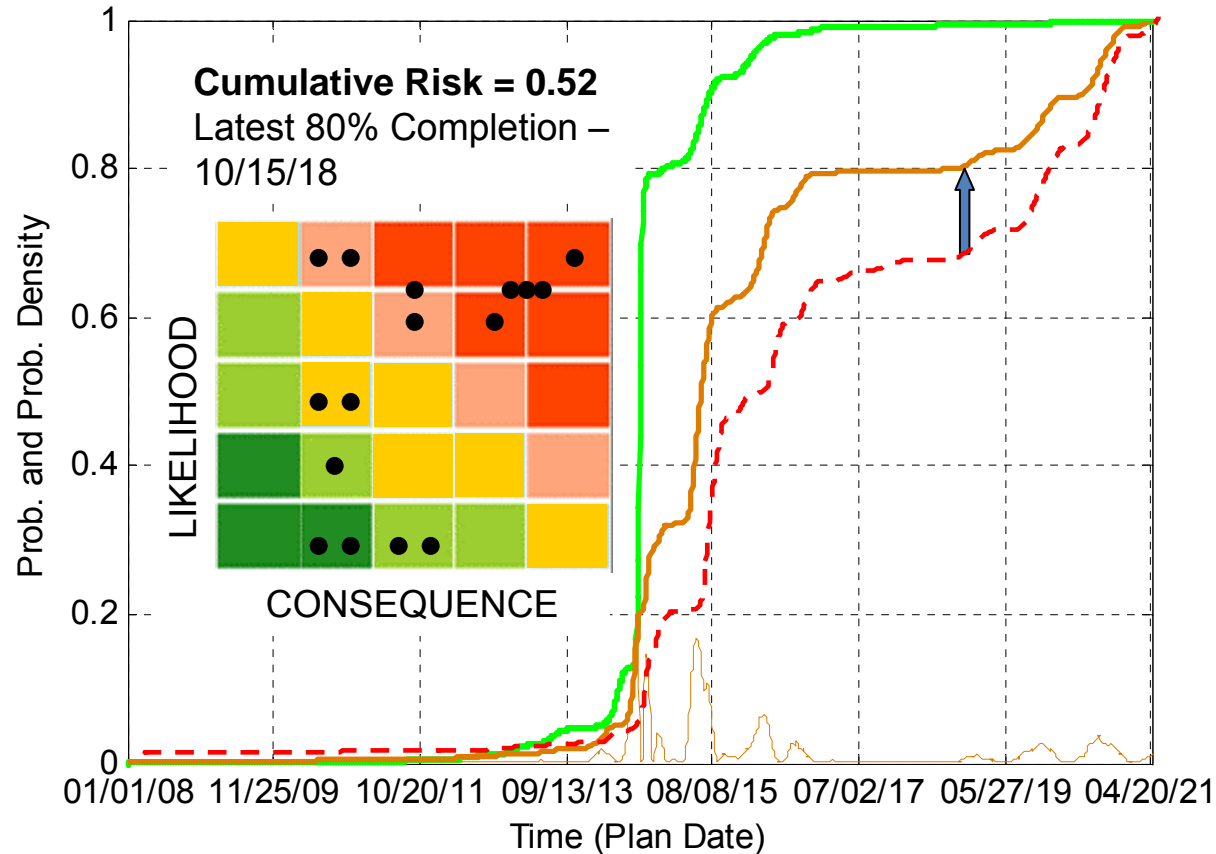
S-curve and Probability Density Risk Expert #1



- Risk is calculated on scale from 0 (no risk - green line) to 1 (maximum risk - red dashed line)
- Risk from one interviewee is illustrated as the brown line



S-curve and Probability Density Risk Expert #2

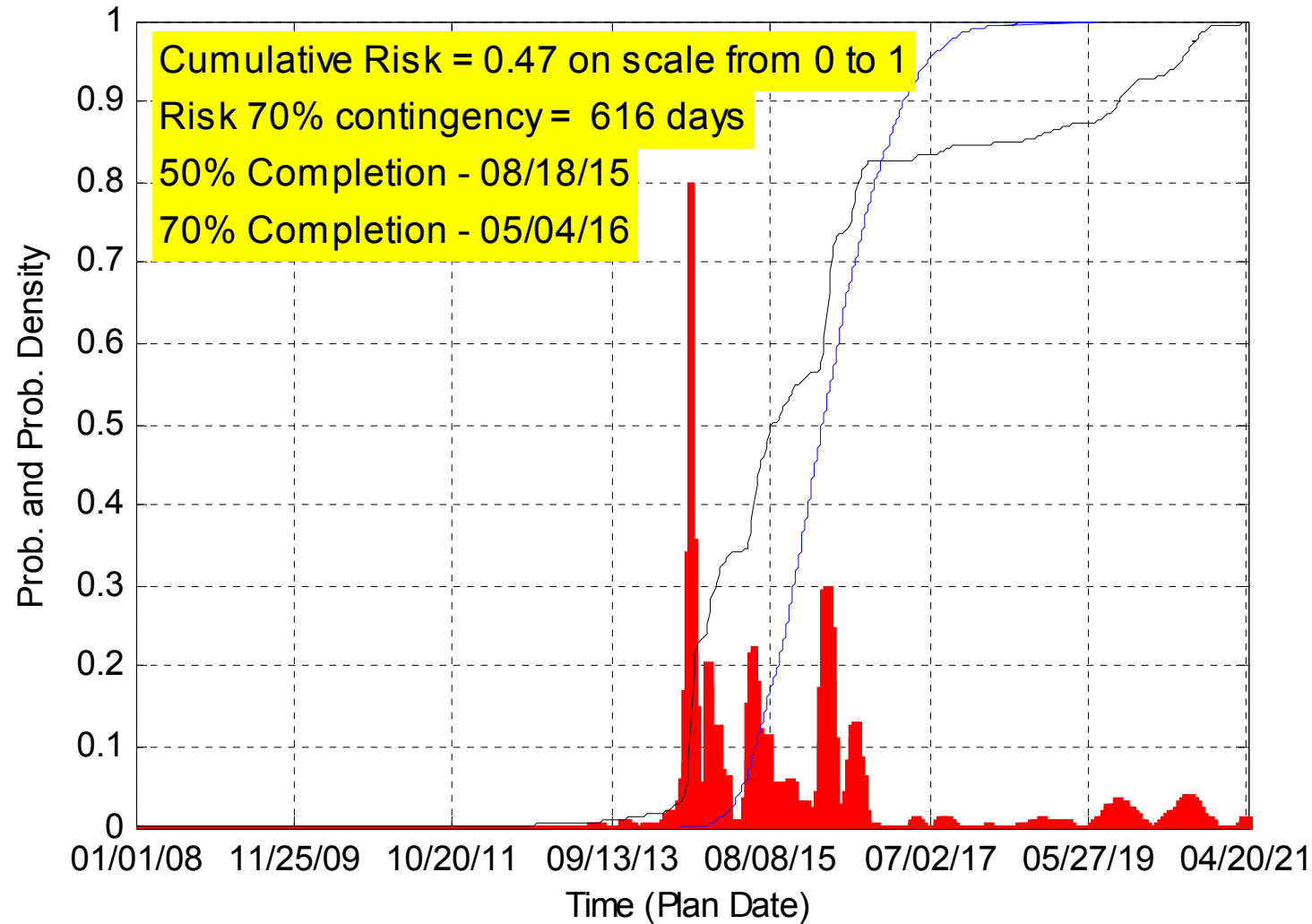


"Shoulder" in S-curve originates from low probability density between end of 2016 and beginning of 2019



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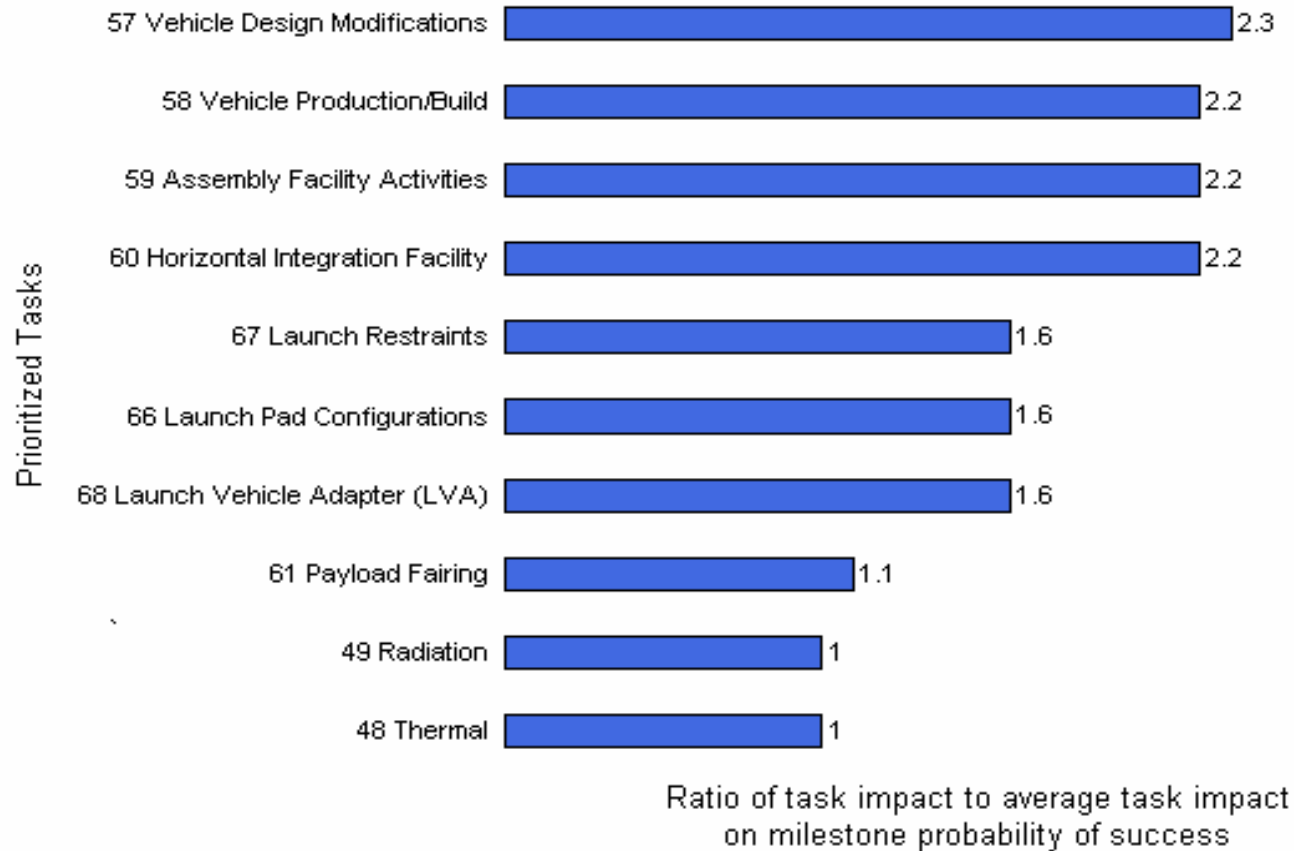
Average of Two Risk Experts Assessments





Quantum Approach Tornado Graph

Prioritized tasks for milestone "Launch(72)"





OVERALL RESULTS



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Summary Comparison Classical and Quantum Schedule Risk Results

	SCHEDULE DATE	DELTA%	50% CL	50% CL	DELTA%	70% CL	70% CL	DELTA%	
			<u>TRADITIONAL</u>	<u>QUANTUM</u>		<u>TRADITIONAL</u>	<u>QUANTUM</u>		
TOTAL PROJECT	27-Aug-14	27-Aug-14	0%	22-Mar-16	18-Aug-15		12-Aug-16	4-May-16	
CONTINGENCY DAYS	0	0	0%	565	351	37.9%	705	607	13.9%
PROJECT START	1-Jan-08	1-Jan-08							
PROJECT DAYS	2396	2396	0%	2961	2747	7.2%	3101	3003	3.2%
CONTINGENCY %				19.1%	12.8%		22.7%	20.2%	



Conclusions & Recommendations

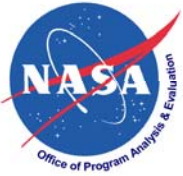


- Overall results indicate comparable performance between “Risk Driver” classical vs quantum approaches to the determination of schedule risk
- There were differences at the 50% and 70% confidence levels
 - Less difference at the 70% level of confidence
- Traditional classical approach is well understood and has shown credible results over many years of application
 - Requires significant effort to construct activity-level triangular distributions
- “Risk Driver” classical approach is straightforward but is relatively new and not as proven as traditional classical approach
 - Requires less effort to construct activity-level triangular distributions
- Quantum approach is new and unproven
 - Requires the least effort to construct activity-level uncertainty distributions
 - Takes advantage of the quantum approaches ability to extract uncertainty out of the project schedule structure itself, through the NIFT-based monte carlo application and implementation of the risk register to generate overall schedule risk
- Recommend early-in-project application of quantum approach as an early indicator with validation from more trusted classical approaches



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BACKUP

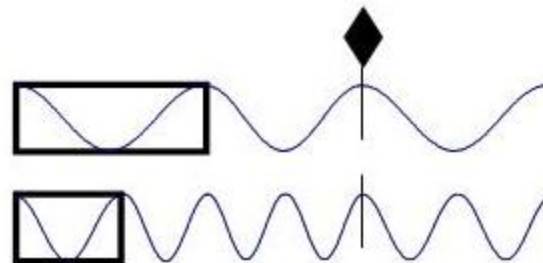


Particle and Wave Characteristics of Project Schedule Tasks



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- The project “task” is the analog to the quantum mechanic’s elementary particle – a photon, for example – and each project task has “wave” and “particle” characteristics
- The task’s “wave” characteristic is illustrated with this diagram:



- Each task “emits” a waveform and all waveforms are “focused” (arrive at the same phase) at the milestone
- The task is also characterized as a particle “ i ”, and the wave associated with it is a wavefunction: $\Psi_i \sim \cos(2\pi t/D)$ where D is task duration (cost and duration of WBS elements are suggested to be proportional to each other) & “ t ” is project time
- The probability that a milestone will meet its planned duration is: $P = [\Sigma(\Psi_i)]^2$

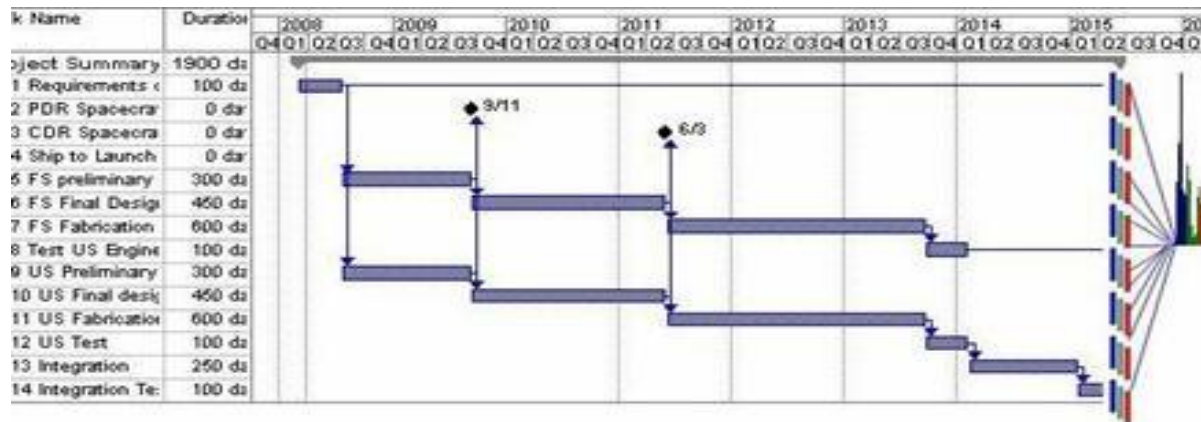


Task-to-Task Correlation as Milestone Collective Image



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- To account for unknown task-to-task correlation, the quantum approach models the milestone as a “*collective image*” of all associated tasks



- Monte carlo simulations provide randomization of variation in task durations in order to “focus” the task *fields* emitted towards the milestone image as each task (each wavelength) contributes to the field intensity at the milestone
 - The milestone image is a diffraction pattern of task wavefunctions (i.e. an “interference” pattern)



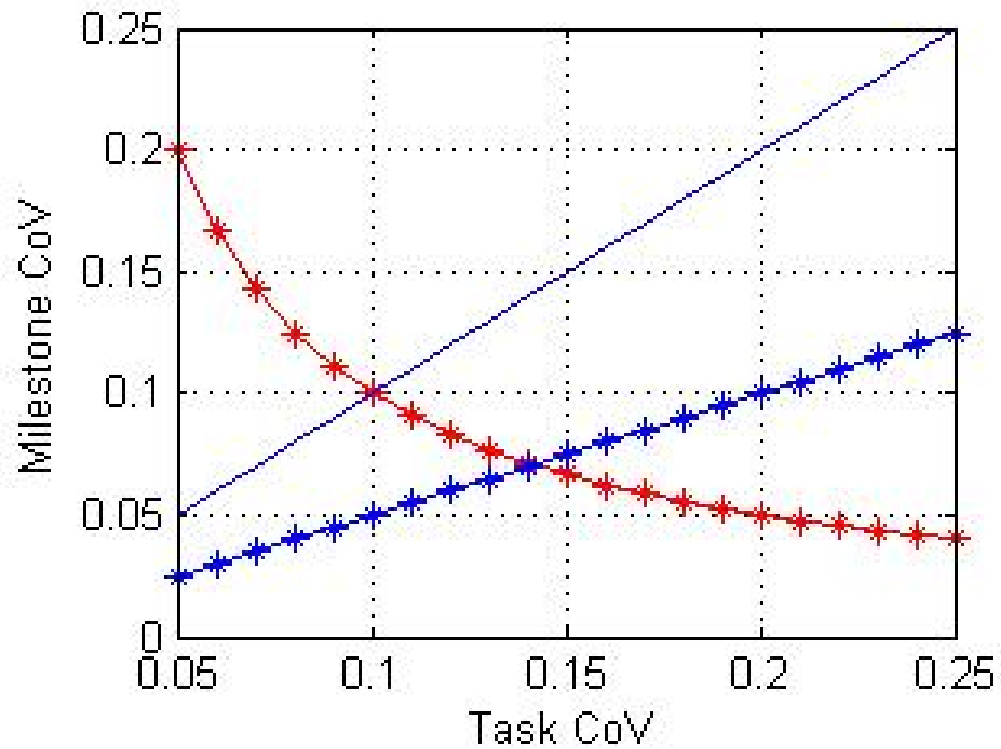
Systematic Right-Shift of Milestone Probability



- Qualitatively, risk is understood as a uni-directional manifestation of uncertainty towards poor project outcome
- The quantum approach introduces risk as a systematic shift of milestone probability as a function of task uncertainty
- The mathematical object describing risk is the milestone correlation function of task wavefunctions
- The correlation function of randomly delayed tasks – using only symmetric duration distributions with the NIFT-based monte carlo – is larger than the correlation function of randomly shortened tasks which causes a systematic right-shift of milestone probability as a function of task uncertainty
- The quantum image of fully symmetric task distributions is thus naturally asymmetric which provides, even without risk driver user input, some measure of expected project delay and cost increase



Relationship of Task CoVs to MS CoVs

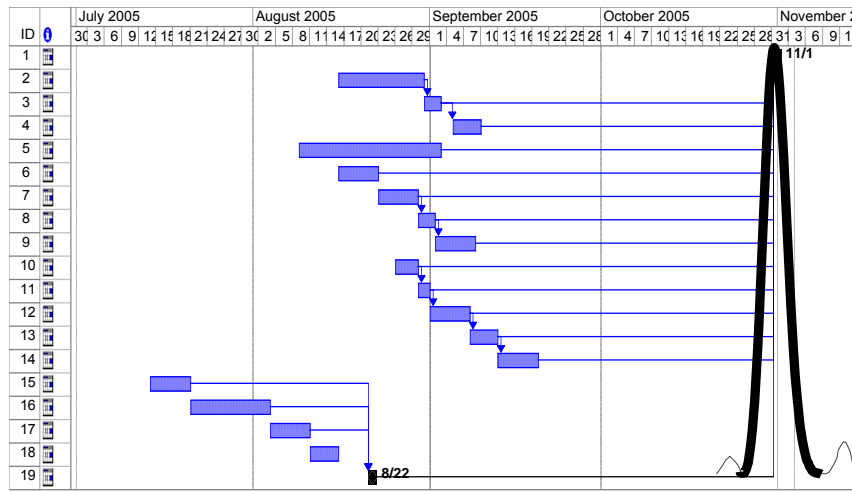




Wave Interference and Milestone Shifts



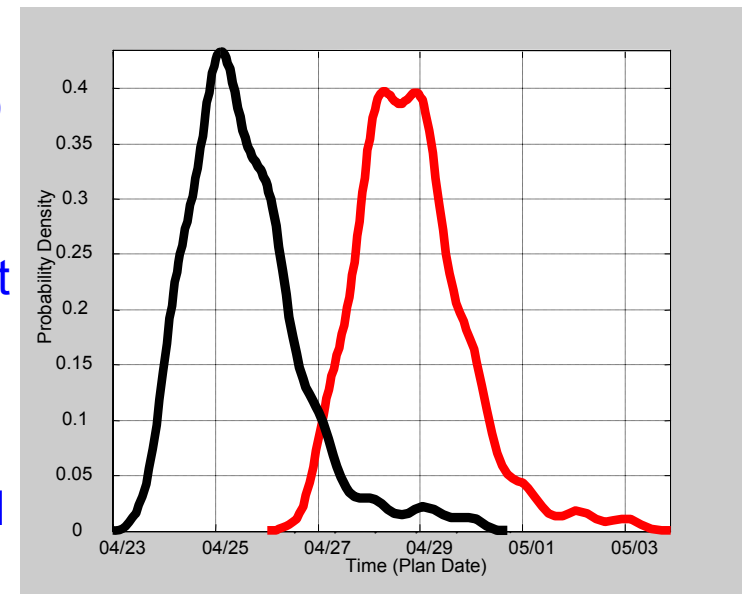
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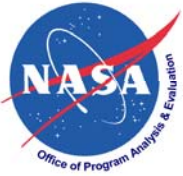


Milestones are modeled by coherent superposition of task wave functions

$$P = [\sum(\Psi_i)]^2$$

- If the top box in the previous chart were to be affected by some kind of risk causing the endpoint to exceed its planned date, its wave function would become out of phase with the planned date of the first milestone and the wave functions would then not be “coherent” or in-phase and destructive “interference” would result precluding meeting the milestone as planned
- The distribution associated with meeting the planned milestone would then be shifted to the right as depicted in the graph to the right





Risk quantification for Slides 22 & 23



The slide presents probability density and S-curve for risk parameters suggested by Expert # 1. Curve is light brown, qualitatively corresponding to cumulative risk factor = 0.41 calculated between limits of 0 (no risk) to 1 (maximum risk). Dashed red is S-curve corresponding to maximum risk.

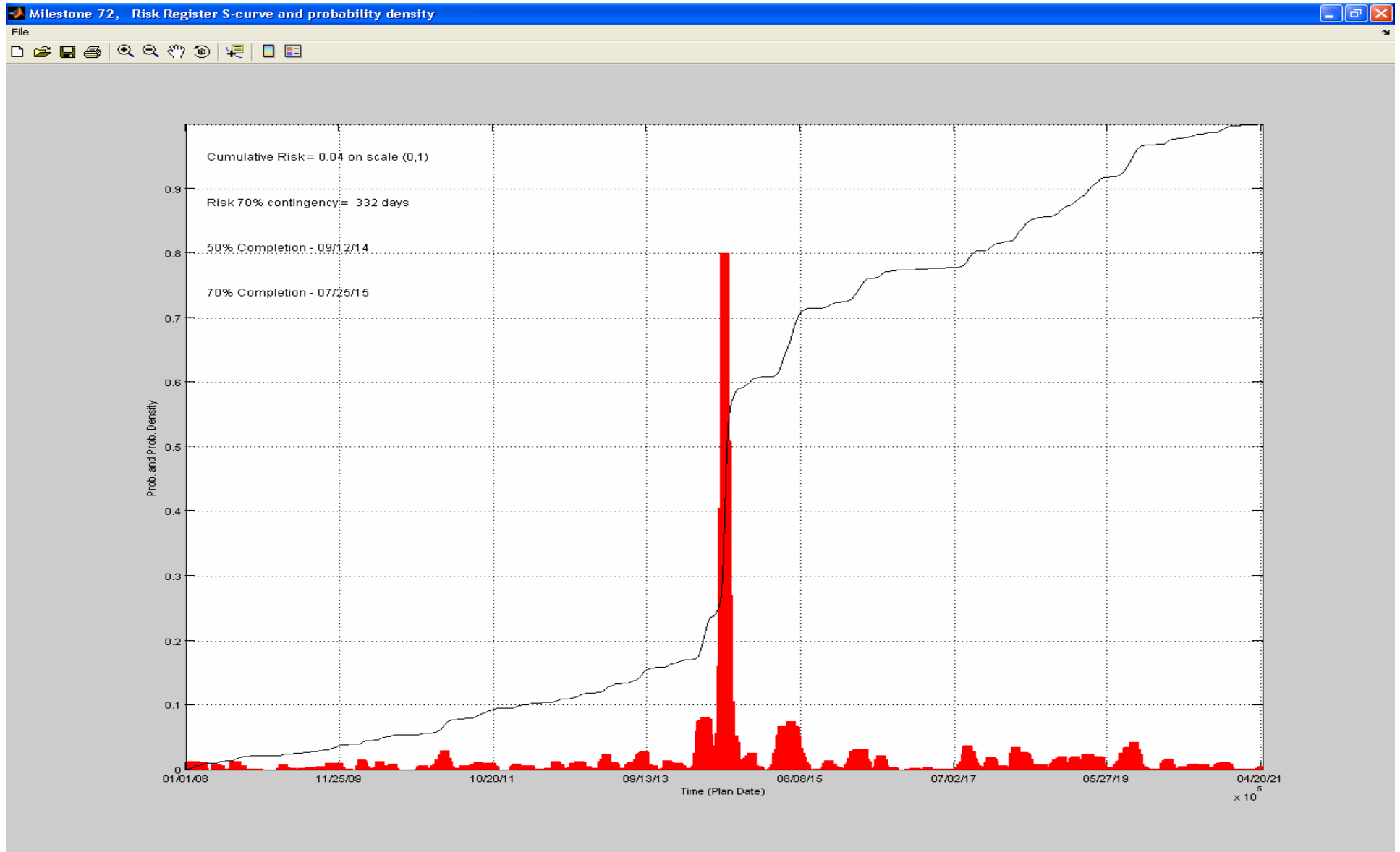
Individual risk likelihoods L and impacts (consequences) I are indicated by dots; cumulative risk R is calculated as

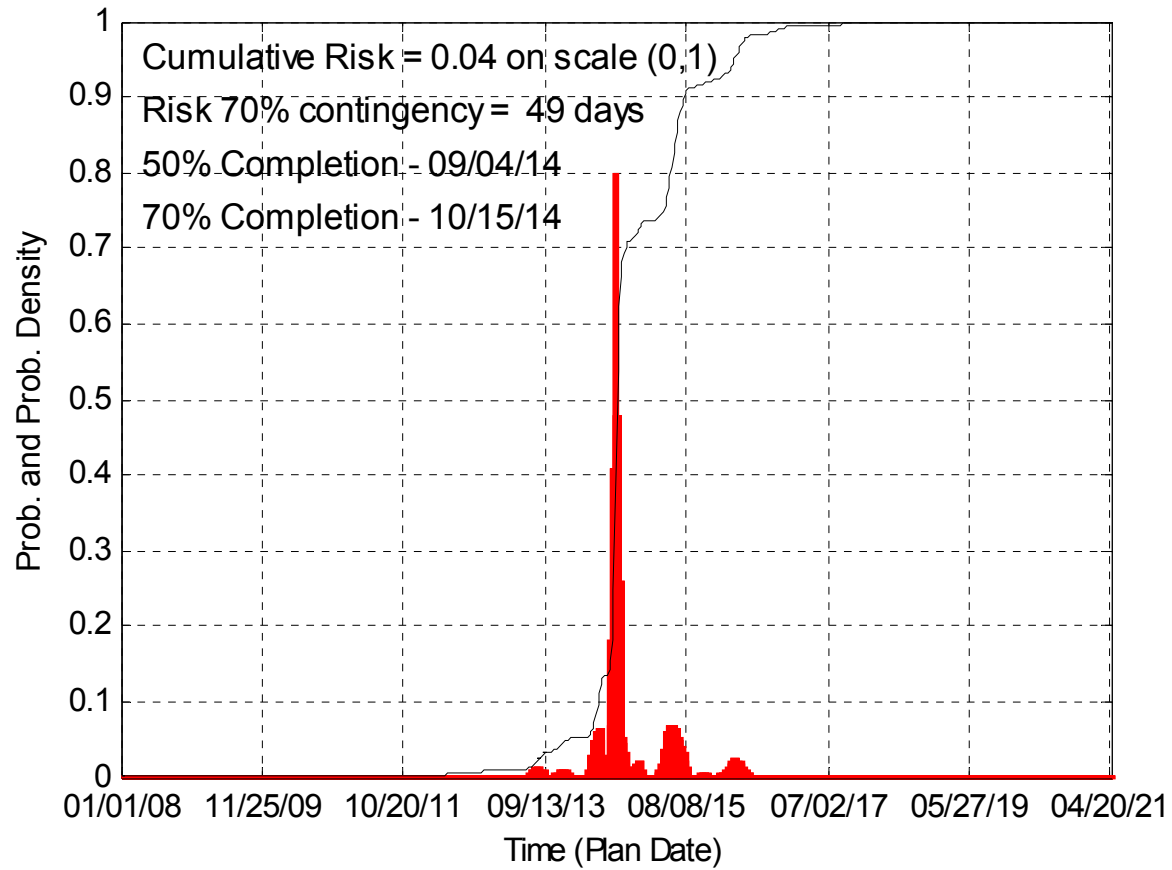
$$R = \sqrt{\frac{1}{N}[(L_1 I_1)^2 + (L_2 I_2)^2 + (L_3 I_3)^2 + \dots + (L_N I_N)^2]}$$

N is total number of risk categories selected. Cumulative risk accumulates as square root of number of risk categories, emphasizing biggest risks and following classical asymptotics.



All Best Case 5X5 Risk Register Inputs CoV Small; S-Curve Very Steep





All Best Case 5X5 Risk Register Inputs

Risk Register

Risk Category	1	2	3	4	5
<input checked="" type="checkbox"/> Launch vehicle uncertainty	1	2	3	4	5
<input checked="" type="checkbox"/> Other	1	2	3	4	5
Management risk					
<input checked="" type="checkbox"/> Multi-Contractor teams and organizational interfaces	1	2	3	4	5
<input checked="" type="checkbox"/> Conflicting schedules and workload	1	2	3	4	5
<input checked="" type="checkbox"/> System testing and retesting	1	2	3	4	5
<input checked="" type="checkbox"/> Geographic distribution of production sites	1	2	3	4	5
<input checked="" type="checkbox"/> Security arrangements	1	2	3	4	5
<input checked="" type="checkbox"/> Under-trained personnel	1	2	3	4	5
<input checked="" type="checkbox"/> Other	1	2	3	4	5

Analysis Summary

MistID	Milestone Name	Milestone Date	# of Tasks	Task CoV (%)	Schedule 70% contingency (days)	50% Completion	70% Completion
<input checked="" type="checkbox"/> 72	Launch	27-Aug-2014	61	9	616	20-Sep-2015	04-May-2016

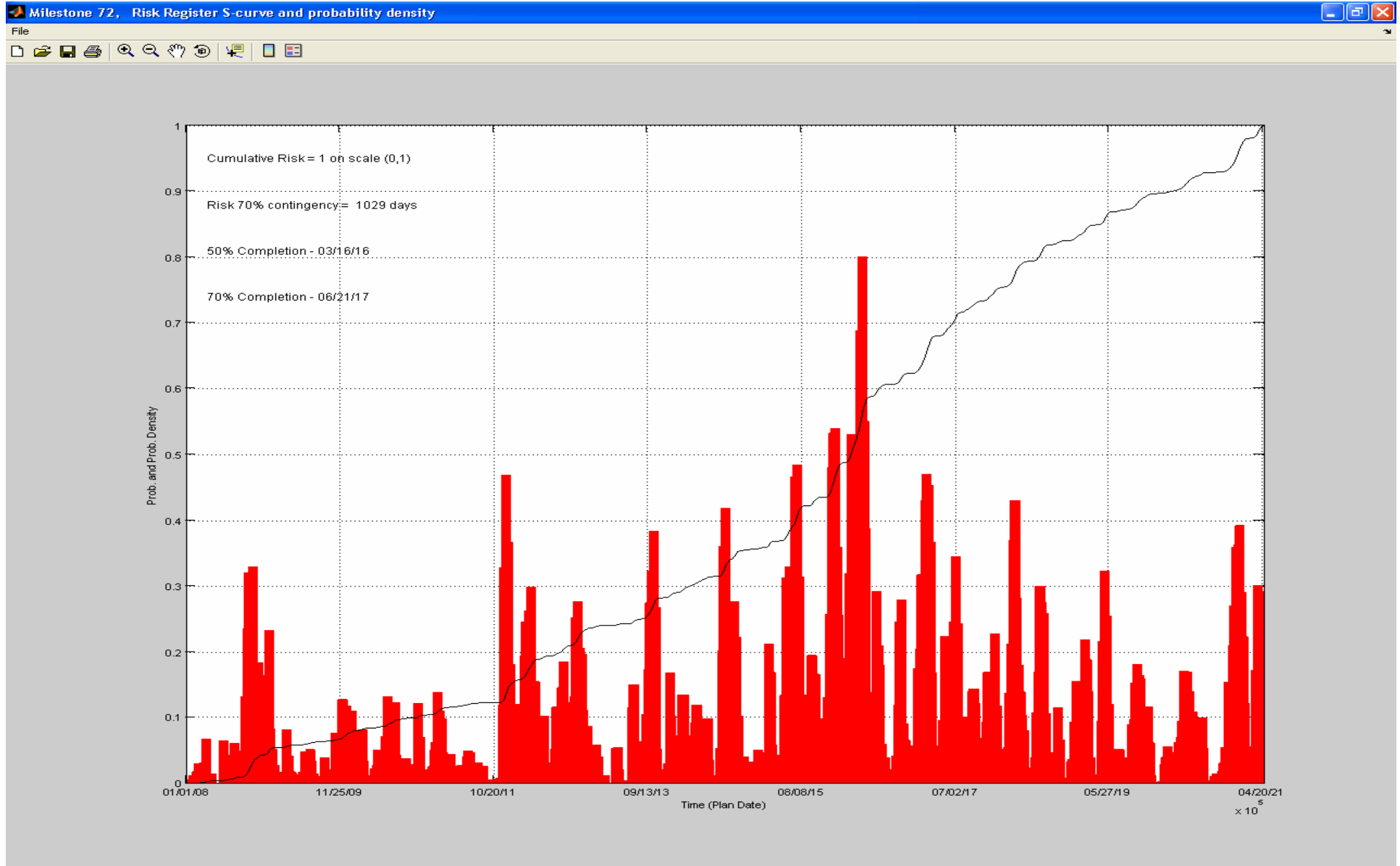
Risk Register input
 Task CoV input
 Schedule risk
 Tornado Chart

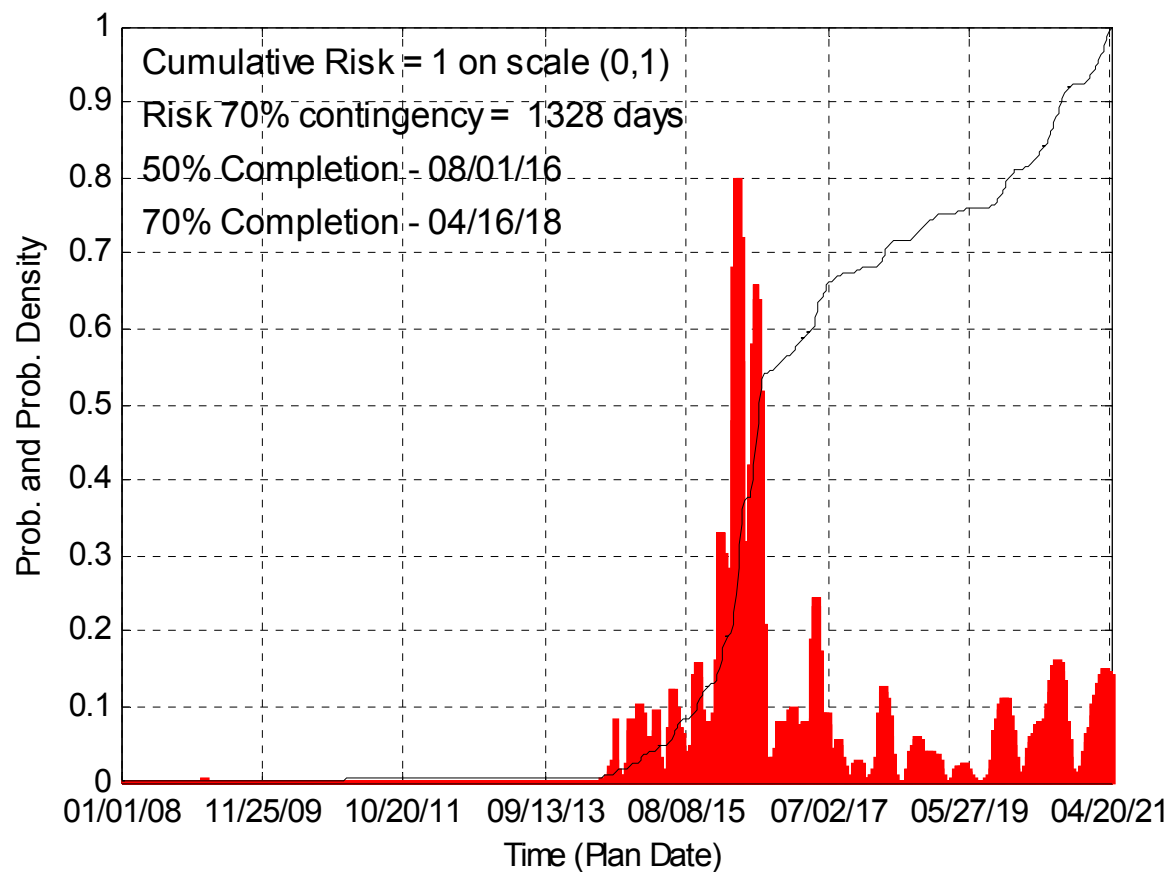


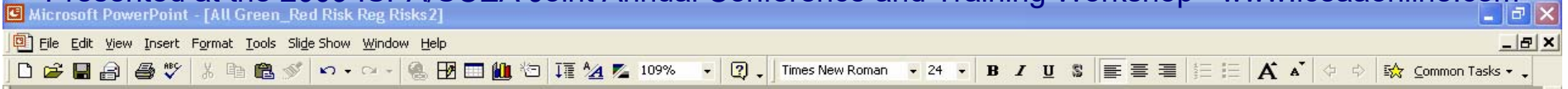
All Worst Case 5X5 Risk Register Inputs Increases CoV; Flattens S-Curve



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All Worst Case 5X5 Risk Register Inputs

Risk Register

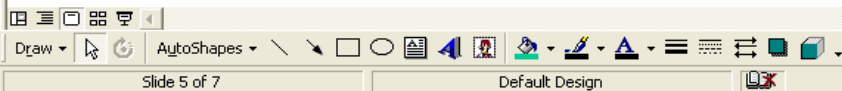
Risk Category	Risk Likelihood and Consequence
<input checked="" type="checkbox"/> Launch vehicle uncertainty	[Green] [Orange] [Orange] [Red] [Red]
<input checked="" type="checkbox"/> Other	[Green] [Orange] [Orange] [Red] [Red]
Management risk	
<input checked="" type="checkbox"/> Multi-Contractor teams and organizational interfaces	[Green] [Yellow] [Orange] [Red] [Red]
<input checked="" type="checkbox"/> Conflicting schedules and workload	[Green] [Yellow] [Orange] [Red] [Red]
<input checked="" type="checkbox"/> System testing and retesting	[Green] [Yellow] [Orange] [Red] [Red]
<input checked="" type="checkbox"/> Geographic distribution of production sites	[Green] [Green] [Yellow] [Orange] [Red]
<input checked="" type="checkbox"/> Security arrangements	[Green] [Green] [Yellow] [Orange] [Red]
<input checked="" type="checkbox"/> Under-trained personnel	[Green] [Green] [Yellow] [Orange] [Red]
<input checked="" type="checkbox"/> Other	[Green] [Green] [Yellow] [Orange] [Red]

Analysis Summary

MistID	Milestone Name	Milestone Date	# of Tasks	Task CoV (%)	Schedule 70% contingency (days)	50% Completion	70% Completion
<input checked="" type="checkbox"/> 72	Launch	27-Aug-2014	61	9	616	20-Sep-2015	04-May-2016

Risk Register input
 Task CoV input
 Schedule risk
 Tornado Chart

Click to add notes

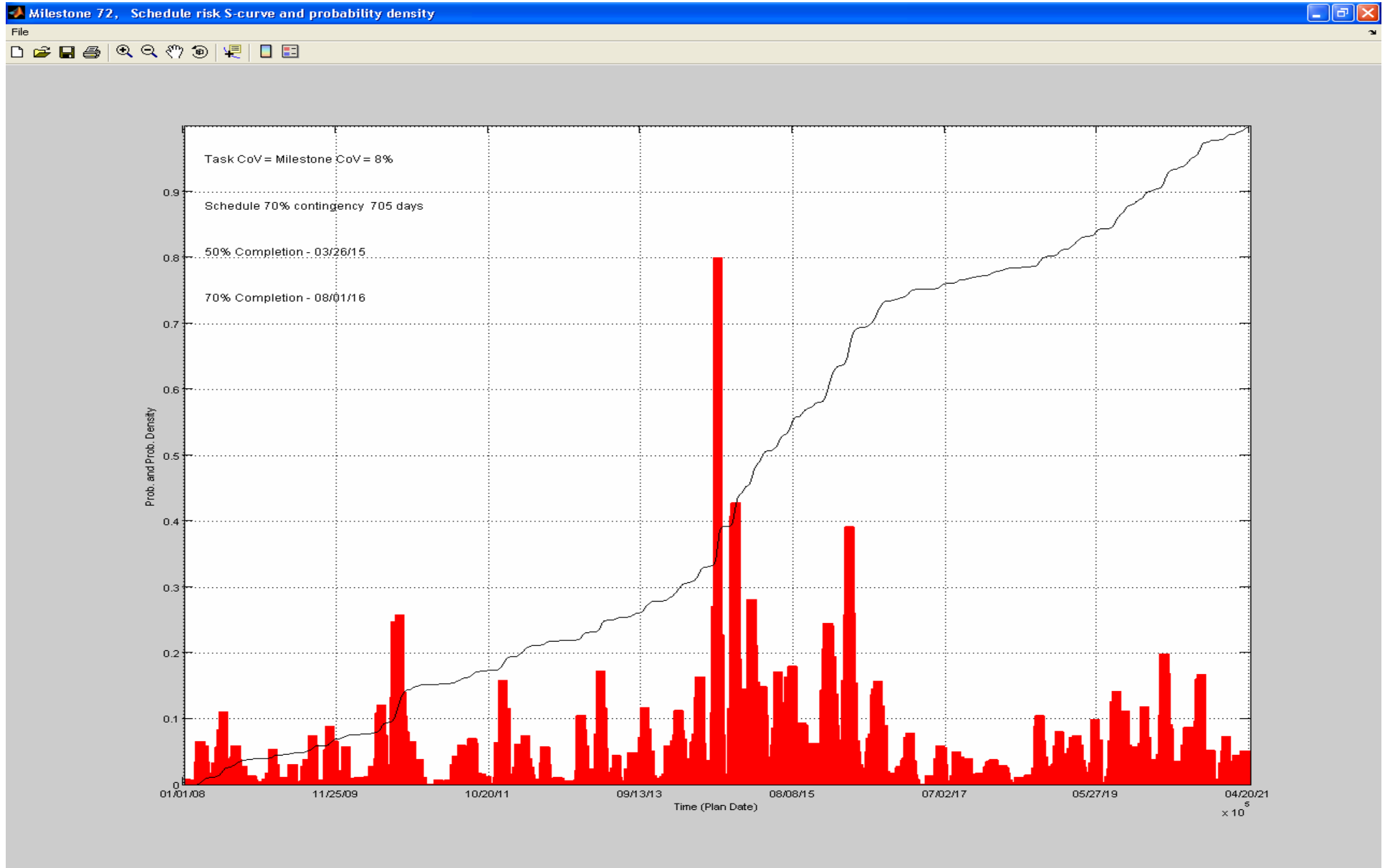




NIFT Monte Carlo Simulations = 3 ("Pure" Quantum Effects on Schedule Risk Only)



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NIFT Monte Carlo Simulations = 300 ("Pure" Quantum Effects PLUS NIFT Monte Carlo)

