

CRITIQUE OF COST-RISK ANALYSIS AND FRANKENSTEIN SPACECRAFT DESIGNS: A PROPOSED SOLUTION

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Cost-Risk Analysis "Best Practice"

To give a sense of "confidence" in a point estimate, cost analysts are expected to generate "credible" probabilistic distributions of potential costs that capture uncertainties associated with cost estimating methodology and cost drivers and account for correlation between cost elements



Each simulation trial results in a set of values for spacecraft subsystems masses, subsystems power loads, and corresponding set of values for subsystems costs

$$\begin{split} M^{i}_{SC} &= \left\{ m^{i}_{j} \right\} = \left\{ m^{i}_{Str}, m^{i}_{Th}, m^{i}_{Propulsion}, m^{i}_{EPS}, m^{i}_{ADS}, m^{i}_{ACS}, m^{i}_{Com}, m^{i}_{CDH} \right\} \\ P^{i}_{SC} &= \left\{ p^{i}_{j} \right\} = \left\{ p^{i}_{Str}, p^{i}_{Th}, p^{i}_{Propulsion}, p^{i}_{EPS}, p^{i}_{ADS}, p^{i}_{ACS}, p^{i}_{Com}, p^{i}_{CDH} \right\} \\ \varepsilon^{i}_{SC} &= \left\{ \varepsilon^{i}_{j} \right\} = \left\{ \varepsilon^{i}_{Str}, \varepsilon^{i}_{Th}, \varepsilon^{i}_{Propulsion}, \varepsilon^{i}_{EPS}, \varepsilon^{i}_{ADS}, \varepsilon^{i}_{ACS}, \varepsilon^{i}_{Com}, \varepsilon^{i}_{CDH} \right\} \\ X^{i}_{SC} &= \left\{ X^{i}_{j} \right\} = \left\{ X^{i}_{Str}, X^{i}_{Th}, X^{i}_{Propulsion}, X^{i}_{EPS}, X^{i}_{ADS}, X^{i}_{ACS}, X^{i}_{Com}, X^{i}_{CDH} \right\} \end{split}$$

The total "simulated" spacecraft system dry mass, power requirement, and cost estimate are

$$M_{SC Total}^{i} = \sum_{j=1}^{8} m_{j}^{i} \qquad P_{SC Total}^{i} = \sum_{j=1}^{8} p_{j}^{i} \qquad X_{SC Total}^{i} = \sum_{j=1}^{8} X_{j}^{i}$$

$$X_j^i = f_j(m_j^i p_{j'}^i) * \varepsilon_{ij}$$

The probability of occurrence of each simulation outcome

$$\forall i, f\left(M_{SC}^{i}, P_{SC}^{i}, \varepsilon_{SC}^{i}, X_{SC}^{i}\right) = \frac{1}{n} \neq 0$$

The Cumulative Density Function

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$$F(M_{SC}^{i}, P_{SC}^{i}, \varepsilon_{SC}^{i}, X_{SC}^{i}) = \sum_{\substack{X_{SC}^{k} \leq X_{SC}^{i}}} f(M_{SC}^{k}, P_{SC}^{k}, \varepsilon_{SC}^{k}, X_{SC}^{k})$$

Probability Distribution to Model Uncertainty



Probability theory is based on concept of event and sample space

Event: value of dice roll

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Sample space: all possible value outcomes associated with rolling a pair of dice

- ≻36 possible outcomes
- > Normalization condition is met:

$$\int_{-\infty}^{+\infty} f(s)ds = \int_{2}^{12} f(s)ds = 1$$

Probability theory is based on the concepts of event and sample space which must be defined before one can attempt to model uncertainty using probability distribution

PÂP Pasadena What's the Meaning of a Measurement or Event in Cost Estimating Experiment? Applied **Physics** What is the "ensemble" or "sample space " of your experiment? Outputs Probability distributions for each cost element in a system's work breakdown structure A cumulative probability distribution of the system's total cos m_{Str}^1 m_{Str}^2 m_{Str}^3 m_{Str}^n m'str Bell curve S curve Confidence lev m_{Th}^3 m_{Th}^1 m_{Th}^2 m_{Th}^n m_{Th}^{l} $m_{Propulsion}^2$ $m_{Propulsion}^3$ $m^1_{Propulsion}$ $m^n_{Propulsion}$ $m_{Propulsion}^{\iota}$ ••• ... TROP m_{EPS}^2 m_{EPS}^1 m_{EPS}^3 m_{EPS}^{i} m_{EPS}^n Cost = x1 + x2 + x3 + ... m_{ADS}^2 m_{ADS}^1 m_{ADS}^3 m_{ADS}^{i} m_{ADS}^n m^2_{ACS} m^1_{ACS} m^3_{ACS} m_{ACS}^{ι} m_{ACS}^n **Cummulative Distribution Function** m_{Com}^1 m_{Com}^2 m_{Com}^3 m_{Com}^i m_{Com}^n 100 $m^1_{C\&DH}$ $m_{C\&DH}^2$ $m_{C\&DH}^3$ 90 $m_{C\&DH}^{\iota}$ $m_{C\&DH}^n$ 80 p_{Str}^2 p_{Str}^1 p_{Str}^3 p_{Str}^{i} p_{Str}^n 70 p_{Th}^1 p_{Th}^2 p_{Th}^3 p_{Th}^n Percentile 60 p_{Th}^{ι} 50 40 p_{Com}^1 p_{Com}^2 p_{Com}^3 p_{Com}^n p_{Com}^{ι} 30 $p_{C\&DH}^1$ $p_{C\&DH}^2$ $p_{C&DH}^3$ $p_{C\&DH}^n$ $p_{C\&DH}^{\iota}$ 20 ε_{Str}^2 ε_{Str}^3 10 ε_{Str}^1 ε_{Str}^{i} ε_{ctr}^n 0 ε_{Th}^2 ε_{Th}^1 ε_{Th}^3 ε_{Th}^{i} ε_{Th}^n \$0 \$50.000 \$100,000 \$150.000 \$200.000 Spacecraft System Cost Estimate (\$K) ε_{Com}^2 ε^{1}_{Com} ε_{Com}^3 ε_{Com}^n ε_{Com}^{i} $\varepsilon^2_{C\&DH}$ $\varepsilon^1_{C\&DH}$ $\varepsilon^i_{C\&DH}$ $\varepsilon^3_{C\&DH}$ $\varepsilon_{C\&DH}^n$ X_{Str}^2 X_{Str}^3 Xⁱ_{Str} X_{Str}^1 X_{Str}^n X_{Th}^2 X_{Th}^3 X_{Th}^1 X_{Th}^i X_{Th}^n • • • . . . outcome of experiment = Spacecraft point design X_{Com}^1 X_{Com}^2 X_{Com}^3 X_{Com}^n XⁱCom and associated cost $X^i_{C\&DH}$ $X^{1}_{C&DH}$ $X^2_{C\&DH}$ $X^3_{C&DH}$ $X^n_{C\&DH}$

Points that make up the s-curve represent not only possible spacecraft cost outcomes but spacecraft design outcomes as well!





There is a Problem....

- Technical design parameters of spacecraft subsystems are <u>interdependent</u>, <u>analytically</u> and <u>implicitly</u> related to one another via key physical relationships
- These key physical relationships are generally not upheld when cost analysts perform cost-risk simulations
- The generated spacecraft point designs (i.e., simulated sets of CER input variables) based on subjective statistics may be neither technically feasible nor buildable (i.e., "Frankenstein" designs)
- Yet all simulation design outcomes are assigned non-zero probability of occurrence and, consequently, the resulting spacecraft system cost CDF is invalid
- \succ The resulting cost-risk assessment may be too high or too low

Design parameters of spacecraft subsystems are related to one another via key physical relationships which are generally NOT upheld in cost-risk simulations



Rocket equation:

$$m_{prop} = M_{SCTotal}^{i} \left[e^{\left(\Delta V / I_{Sp} g \right)} - 1 \right],$$

> Solar array sizing equation:

$$A = \frac{P_{EOL}}{F_S f_p \varepsilon_{BOL} (1.0 - \delta_{los}) [1.0 - \gamma_T (t_0 - t_{REF})] \cos(\alpha) (1.0 - \beta)^T},$$

Stefan-Boltzmann law:

$$A = \frac{Q}{\sigma T^4},$$

Some of the randomly generated spacecraft point designs based on subjective statistics are not technically feasible, buildable, or flyable. Yet they are assigned non-zero probability of occurrence and consequently costrisk assessment is invalid



The Problem Pictorially...



Points on S-curve may represent cost of a Frankenstein spacecraft Design!





NASA's Data Collection to Support Analysis Work

The Importance of NASA Data Collection

Data Collection and Tool Provision are essential to improving NASA-wide cost analysis capabilities. Funding these capabilities is a top priority of the Cost Analysis Division

Data Collection

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- The Cost Analysis Data Requirement (CADRe) the 'flight recorder' for <u>all</u> major NASA programs and projects provides data that is the foundational life blood of NASA's cost analysis capabilities.
- CADRe data collected temporally at six major project milestones supports analysis and decision making for all major NASA acquisitions, and provides the basis for the Agency's external commitments, but depends on the ONCE database to make the data accessible.
- NASA's programmatic performance has been improving over the last decade, enabled by CADRe data, and continued collection of this essential temporal data is. high priority and must continue.

Provides Basis for Tool Provision

- CAD funds key <u>workhorse</u> estimating tools that are used NASA-wide by the agency's cost analysis community and essential for all cost analysis done at the Centers.
- Included are NASA-developed tools (NAFCOM/PCEC and NICM) and commercially available tools (e.g. PRICE, JACS, POLARIS, SEER).
- CAD standardizes tool use and maximizes efficiency for NASA through agency-wide licenses.
- Cost analysis capabilities across the agency would be crippled without these tools.





Cost Analysis Data Requirement (CADRe)

A three-part document:

- Part A: Describes a NASA project at each milestone (SRR, PDR, CDR, SIR, Launch and End of Mission), and describes significant changes that have occurred.
- Part B: Contains standardized templates to capture key technical parameters that are considered to drive cost (Mass, Power, Data Rates).
- Part C: Captures the NASA project's Cost Estimate and actual life cycle costs within the project's and a NASA Cost Estimating Work Breakdown Structures (WBS).



 Note: THE "LAUNCH" CADRes for a mission captures the final costs and as-built mass, and power data. The SRR, PDR, CDR CADRes contain Current Best Estimates.



When Are CADRes Required?



CADRe is updated at each indicated milestone starting with SDR/MDR

Program Phases		Formulation		Implementation			
	KDP A	KDP B	KDP C	KDP D	KDP E		
Flight Projects Life Cycle Phases	Pre-Phase A : Concept Studies	Phase A: Concept Development	Phase B: Preliminary Design	Phase C: Detailed Design	Phase D: Fabrication, Assembly & Test	Phase E: Operations & Sustainment	Phase F: Disposal
		SDR/MDR	PDR	CDR	SIR Launch		EOM
Traditional Directed Missions			73			()	Ô
AO-Driven Projects	Dov Sel Ste	vn ect Selec p 1	ct Step 2		$\langle \rangle$	\$	Ò

Legend

Key Decision Point (KDP)



All parts of CADRe due 30-45 days after KDP B



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CADRe delivered; based on Concept Study Report (CSR) and winning proposal



Update as necessary 30-45 days after CDR using CDR material

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Update as necessary 30-45
 days after KDP D using
 SIR material

 CADRe, All Parts due
 90 days after launch, based on as built or as deployed configuration



CADRe Customers (Beneficiaries)



	Internal NASA Customers	
SMD	Various SMD Cost Studies and Analysis of Projects	External
SOMA	Reviewing AO proposals	NASA Customers
SID	Portfolio Modeling; Rapid Cost/Schedule Assessing	
GSFC	Flight Projects, RAO, Explorers Office, Integrated Design Center,	Air Force GAO
IPAO	Historical Data, Assessment support	
MSFC	Cost Model Development and Calibrations	NRO NOAA
LaRC	Cost research, Used by TMCO Panel for AO reviews	OMB DNI
APL	Cost Engineering Trades	
JPL	TEAM X Cost Engineering Trades	
CAD	Cost/Schedule Improvement, Policy Improvement, JCL Improvement Model Calibration, Research and Tool Development	



What is One NASA Cost Engineering Database?



- Cloud Compliant Database that automates the Search and Retrieval of CADRe Data
 - Active Server Pages utilizing: Microsoft SQL Server 2005 database; .NET framework; VB.Net; C#; Javascript; VBScript
- ONCE is a powerful tool for searching CADRe data across multiple NASA projects
- Able to simultaneously pull data across multiple projects, milestones, and tech data fields (mass, power, etc)
- Easy navigation to any desired CADRe, able to produce customized reports.
- Filtering features in ONCE provide an easy way to obtain the information needed quickly
- After retrieving the desired data, it is easy export to excel or nearly any statistical package to perform regression analysis
 - ONCE helps order and access the CADRe (flight recorder) data, transforming it into useful information.



One Solution: Spacecraft Probabilistic Cost Growth Model





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Growth in cost drivers (i.e. spacecraft mass) can be captured by applying appropriate spacecraft cost growth factor

Spacecraft Probabilistic Cost Growth Model in a Nutshell



- Model does not require cost driver uncertainty input
- Requires only two parameters:

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- Current Best Estimate(CBE) of spacecraft system cost
- CBE maturity relative to project milestones, which is reasonably objective
- ➢ Based on historical analogous systems (available in NASA CADRe database)
- Predicts spacecraft system cost growth (or shrinkage)
- Produces cost growth factor distribution result (embodies uncertainty) that recognizes the possibility of growth or shrinkage of cost driver (i.e. spacecraft design parameters)

Provides probabilistic cost growth adjustment to spacecraft cost CBE

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Study Dataset



NASA Project	CSR/SRR	PDR	CDR
CONTOUR	N/A	Х	Х
MESSENGER	Х	Х	Х
New Horizons	Х	Х	Х
STEREO	Х	Х	Х
AIM	Х	Х	Х
AQUA	Х	Х	Х
CHIPSat	Х	Х	N/A
EO-1	Х	N/A	Х
GLAST	Х	Х	Х
IBEX	Х	Х	Х
LRO	N/A	Х	Х
RHESSI	Х	Х	Х
SWAS	Х	Х	Х
Terra	Х	Х	Х
TRACE	Х	N/A	N/A
TRMM	Х	Х	Х
CloudSat	X	X	X
MRO	Х	X	X
Spitzer	Х	X	X

19 Earth-Orbiting and Deep Space Missions Obtained from NASA CADRe Database



Model Development Approach

 Developed spacecraft system cost change database

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- 2) Performed exploratory analysis to uncover appropriate fit distribution
- Fit lognormal PDF to our spacecraft system cost growth data
- 4) Developed Empirical Cumulative Distribution Functions (ECDF) of spacecraft cost Growth Factor (GF) for various project milestones

 $SC Cost Change_{MS} = \frac{SC Cost_{Launch} - SC Cost EAC_{MS}}{SC Cost EAC_{MS}}$, where MS = CSR, PDR, CDR,

 $SC Cost GF_{MS} = 1 + SC Cost Change_{MS}$



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Spacecraft Probabilistic Cost Growth Model





$$f(x|\mu,\sigma) = \frac{1}{x\sigma\sqrt{2\pi}} \exp\{\frac{-(\ln x - \mu)^2}{2\sigma^2}\} \ ; \ x > 0.$$

Decreasing mean growth factor and growth factor uncertainty (decreasing CV) as estimate relative maturity increases

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- 1. Determine spacecraft subsystem cost drivers (mass or other key technical parameters) and obtain their CBE values
- 2. Plug these values in the appropriate spacecraft subsystem CERs, ignoring their contingency values
- 3. Develop cost probability distributions of spacecraft subsystems to model uncertainty associated with the cost methodology only
- 4. Account for correlation between costs of various spacecraft subsystems
- 5. Perform simulation, use the "rollup procedure" and generate the overall spacecraft system cost distribution.
- 6. Select the appropriate spacecraft cost growth factor distribution based on where in the mission development life cycle the spacecraft cost CBE is being generated.
- 7. Adjust the resulting spacecraft cost probability distribution by combining it with the selected spacecraft cost growth factor distribution
- 8. Use the resulting cost probability distribution to assess the percentile or "confidence" level associated with a point estimate
- 9. Recommend sufficient cost reserves to achieve the percentile or level of "confidence" acceptable to the project or organization
- 10. Allocate, phase, and convert a risk-adjusted cost estimate to then-year dollars



Conclusions



- Cost analysts need to understand that while spacecraft design parameters are not typically known with sufficient precision, their uncertainties should NOT be modeled with subjective distributions
 - Let's not abuse theory of probability! Know what you are simulating, define your event and sample space
- Spacecraft subsystem design parameters are analytically and implicitly related by physical and engineering relationships
- One suggested solution is probabilistic growth cost model which embodies cost driver uncertainty
- System-of-systems cost models should ensure the validity of their input vectors
- Be wary of traditional cost estimate S-curve, it's just a measure of an individual's belief
- We will always lack the normalization condition unless we find a way to apply Quantum Field Theory in cost-risk analysis!!!







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Questions?





Backup Slides

Spacecraft Cost and Mass Growth Dataset and Summary Statistics at MS-CSR



CSR		
Mission	SC Cost GF	SC Mass GF
MESSENGER	187%	166%
New Horizons	185%	125%
STEREO	154%	116%
AIM	137%	98%
CHIPSat	105%	93%
IBEX	159%	146%
RHESSI	147%	122%
SWAS	153%	137%
TERRA	143%	119%
CLOUDSAT	201%	126%
MRO	132%	146%
SPITZER	130%	150%
AQUA	82%	121%
EO-1	205%	183%
GLAST	111%	111%
TRACE	68%	124%
TRMM	100%	100%
WIRE	107%	83%
Observations	18	18
Mean	139%	126%
Median	140%	123%
STDEV	39.52%	25.61%
Min	68%	83%
Max	205%	183%

Spacecraft Cost and Mass Growth Dataset and Summary Statistics at MS-PDR



PDR			
Mission	SC Cost GF	SC Mass GF	
COUNTOUR	94%	101%	
MESSENGER	135%	128%	
New Horizons	122%	137%	
STEREO	132%	121%	
AIM	129%	97%	
AQUA	104%	120%	
CHIPSat	84%	125%	
GLAST	130%	119%	
IBEX	143%	134%	
LRO	127%	113%	
RHESSI	147%	126%	
SWAS	110%	102%	
TERRA	129%	105%	
TRMM	115%	118%	
CLOUDSAT	169%	97%	
MRO	128%	124%	
SPITZER	175%	149%	
Observations	17	17	
Mean	128%	119%	
Median	129%	120%	
STDEV	23.43%	14.63%	
Min	84%	97%	
Max	175%	149%	

Spacecraft Cost and Mass Growth Dataset and Summary Statistics at MS-CDR



CDR			
Mission	SC Cost GF	SC Mass GF	
COUNTOUR	105%	94%	
MESSENGER	133%	113%	
New Horizons	107%	119%	
STEREO	124%	112%	
AIM	139%	101%	
AQUA	121%	105%	
EO-1	137%	105%	
GLAST	110%	108%	
IBEX	112%	122%	
LRO	120%	108%	
RHESSI	147%	120%	
SWAS	121%	101%	
TERRA	113%	102%	
TRMM	117%	109%	
CLOUDSAT	136%	100%	
MRO	124%	108%	
SPITZER	166%	125%	
Observations	17	17	
Mean	126%	109%	
Median	121%	108%	
STDEV	15.91%	8.45%	
Min	105%	94%	
Max	166%	125%	

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Empirical Cumulative Distribution Function of Spacecraft Cost Growth Factor



CSR		
%ile	SC Cost GF	
5%	0.68	
11%	0.82	
21%	1.05	
26%	1.07	
32%	1.11	
37%	1.30	
42%	1.32	
47%	1.37	
53%	1.43	
58%	1.47	
63%	1.53	
74%	1.54	
79%	1.59	
89%	1.87	
95%	2.01	



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Empirical Cumulative Distribution Function of Spacecraft Cost Growth Factor



PDR		
%ile	SC Cost GF	
6%	0.84	
13%	1.04	
19%	1.10	
25%	1.15	
31%	1.22	
38%	1.27	
44%	1.28	
50%	1.29	
56%	1.29	
63%	1.30	
69%	1.32	
75%	1.35	
81%	1.43	
88%	1.47	
94%	1.69	



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Empirical Cumulative Distribution Function of Spacecraft Cost Growth Factor



CDR		
%ile	SC Cost GF	
6%	1.07	
13%	1.10	
19%	1.12	
25%	1.13	
31%	1.17	
38%	1.20	
44%	1.21	
50%	1.21	
56%	1.24	
63%	1.24	
69%	1.33	
75%	1.36	
81%	1.37	
88%	1.39	
94%	1.47	



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Before CADRe:

- NASA had <u>no</u> repository of historical project programmatic, schedule, cost, and technical data.
- Programmatic history of NASA projects were not captured systematically.
- Cost Estimates were developed <u>without</u> understanding past history, so quality of cost estimates suffered.
- Cost Research efforts were limited and inconclusive without meaningful data.
- In family checks against other completed projects was difficult and not readily performed with any consistency.
- When cost data was collected, the data was not made available for other project estimating exercises.

With CADRe:

- NASA now has a generous repository of specific Cost, Technical, Schedule data to support cost estimating for future projects.
- NASA can now better evaluate future AO proposals to help determine which proposals are in family with history and better explain reasons for differences.
- Helps NASA PM record in a formal agency document key events that occurred during the project (both internal & external).
- Helps PMs understand relevant heritage and previous risk postures, and schedule durations when building their own baselines.
- CADRe allows for performing advanced cost research which was not possible previously (ie, Optimum Cost Phasing, Expl of Change, Dashboard Sheets).